Discussion on *"Inferring the number of components in a mixture: dream or reality?"* by prof. Christian Robert

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• A set of random variables Y_1, \ldots, Y_n are sampled from mixture model if

$$(Y_i \mid \boldsymbol{\pi}, \boldsymbol{\theta}) \stackrel{\text{iid}}{\sim} \sum_{h=1}^{H} \pi_h \mathcal{K}(y \mid \boldsymbol{\theta}_h),$$

where π_1, \ldots, π_H are probabilities and $\mathcal{K}(y \mid \theta)$ is a density (kernel).

Mixture models are powerful but delicate tools.

Normal deviate: Larry Wasserman's blog

"I have decided that mixtures, like tequila, are inherently evil and should be avoided at all costs."

Scientific productivity

- Number of papers authored by prof. Christian Robert, according to Scopus: 167.
- Number of papers read by Aliverti and Rigon, combined: ~ 150.

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Citations

- Number of citations of prof. Christian Robert, according to Scopus: 6246.
- Number of citations of Aliverti and Rigon, combined: NA.

Learning the number of clusters

- An important application of mixture models is model-based clustering. Reliably learning the number of clusters has entertained a generation of statisticians!
- Caveat. The number of clusters K_n does not coincide with the number of components H. The quantity $K_n \leq H$ is the number of non-empty groups among the cluster indicators.
- This is quite evident in Bayesian nonparametrics, where could have $H = \infty$.
- Can we learn the true number of clusters *H*₀ from the data? Yes, but under many assumptions and being very careful to prior choices, identifiability issues, etc.

Biased list of references

- Rousseau, J., & Mengersen, K. (2011). Asymptotic behavior of the posterior distribution in overfitted mixture models. *Journal of the Royal Statistical Society. Series B: Statistical Methodology*, 73(5), 689–710.
- Miller, J. W., & Harrison, M. T. (2014). Inconsistency of Pitman-Yor process mixtures for the number of components. *Journal of Machine Learning Research*, 15, 3333–3370.
- Ascolani, F., Lijoi, A., Rebaudo G. & Zanella G. (2022). Clustering consistency with Dirichlet process mixtures. *Biometrika* (in press)

Overclustering and misspecification I



- Data displayed above are the "true labels".
- If the kernel is wrong, the estimation of K_n using a mixture model is unreliable.

Overclustering and misspecification II



■ In practice, one often get too many clusters, compared to *H*₀. This is exacerbated in high-dimensional settings when misspecifications are more likely to occur.

Misspecification of the kernel: does it matter?

Remark. Even when the kernel is wrong, the **density** may be reliably estimated.



Reference

 Lijoi, A., Prünster, I., & Walker, S. G. (2005). On consistency of nonparametric normal mixtures for Bayesian density estimation. *Journal of the American Statistical Association*, 100(472), 1292–1296.

- If the multivariate Gaussian kernel is inappropriate, can't we use something else? Yes, but that's not easy!
- Parametric choices (e.g., multivariate skew-normals, etc.) may mitigate the problem and/or protect against outliers, often at the price of increasing the computational burden.
- What about nonparametric kernels? Mixture of mixtures are fully nonparametric models, but some serious identifiability difficulties must be addressed.

References

- Mukhopadhyay, M., Li, D., & Dunson, D. B. (2020). Estimating densities with non-linear support by using Fisher–Gaussian kernels. *Journal of the Royal Statistical Society. Series B: Statistical Methodology*, 82(5), 1249–1271.
- Scarpa, B., & Dunson, D. B. (2014). Enriched stick-breaking processes for functional data. *Journal of the American Statistical Association*, 109(506), 647–660.
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Generalized Bayes clustering

- An "alternative" to Bayesian mixture models are Gibbs posteriors. The key idea is the usage of a generic loss function instead of a genuine likelihood.
- A generalized Bayes product partition model is

$$\pi(c \mid \lambda, Y) \propto \pi(c) \prod_{h=1}^{H} \exp \left\{ -\lambda \sum_{i \in C_h} \mathcal{D}(y_i; \mathbf{Y}_h) \right\}, \quad c : |C| = H,$$

where $\mathcal{D}(y_i; Y_h) \ge 0$ quantifies the **discrepancy** of the *i*th unit from the *h*th cluster

This may result in more robust models (depending on the chosen loss!) and gives you more modeling freedom. Gibbs posteriors also have intriguing connections with ABC.

Reference

- Miller, J. W., & Dunson, D. B. (2018). Robust Bayesian Inference via Coarsening. *Journal of the* American Statistical Association, 1459.
- Rigon, T., Herring, A. H. and Dunson, D. B. (2022+). A generalized Bayes framework for probabilistic clustering. *Submitted*.



- Learning the number of clusters K_n is a difficult (but not impossible!) problem that crucially relies on the correct specification of the kernel.
- Even when we trust the kernel, identifiability issues complicate the estimation problem.
- Thank you Christian for the very nice talk!