

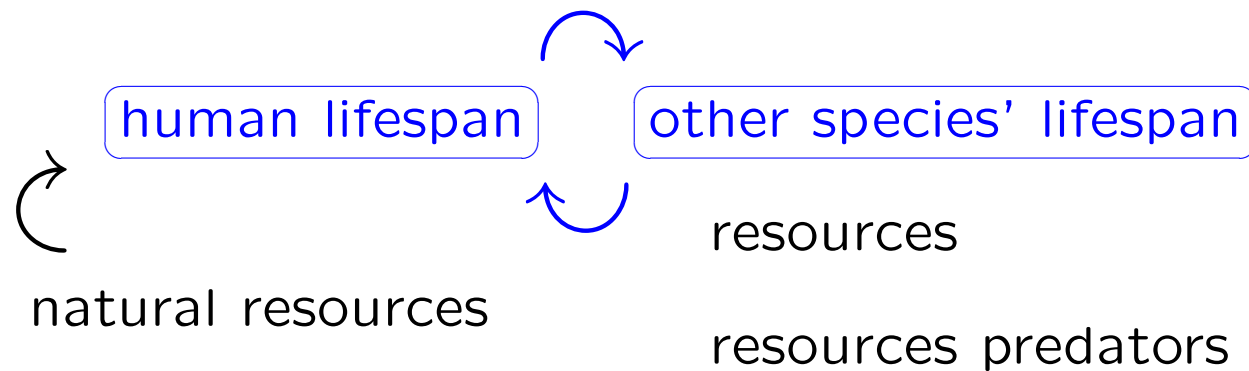
**TOWARDS A TRANSDISCIPLINARY FRAMEWORK  
TO ANALYZE BIRTH AND DEATH PATTERNS.  
DISCUSSION**

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- ▣▶ *Understanding the nature and extent of **biological** constraints on the rate of ageing [..] is critical [...] to extend human lifespans... (Colchero et al., 2021)*
- ▣▶ *Under what conditions could the rate of ageing change?*

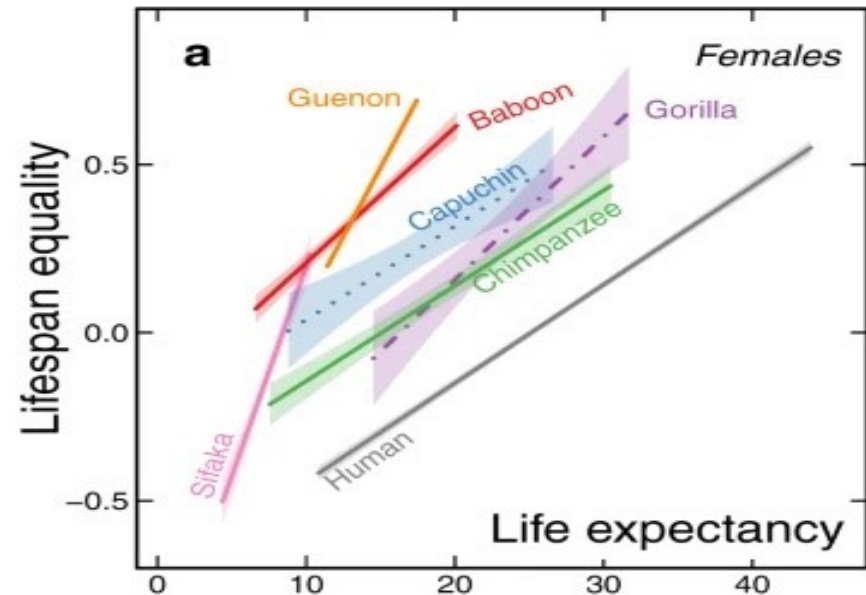
Colchero, F., et al. (2021). The long lives of primates and the 'invariant rate of ageing' hypothesis. *Nature Communications*, 12, 3666.

Pace & Shape as two different components of mortality  
separate estimates ignore interactions?



## DEVIATIONS MAY BE DUE TO EXTERNAL CONDITIONS

- interactions among species  
(e.g., human effect on environment)
- extemporaneous events  
(e.g., pandemic, war, extreme climatic events)
- limited resources



Colchero, F., et al. (2021). The long lives of primates and the 'invariant rate of ageing' hypothesis. *Nature Communications*, 12, 3666.

## Alternative [unfeasible?] approach

3 species extended Lotka Volterra models; among others:

- ➡ Chauvet et al. (2002), *Mathematics Magazine*
- ➡ Hsu S.B. et. al.(2015) *Journal of Mathematical Analysis and Applications*

Chauvet, E., Poullet, J. E., Previte, J.P. and Walls, Z. (2002). A Lotka-Volterra Three-species Food Chain, *Mathematics Magazine*, 75(4), pp. 243-255.

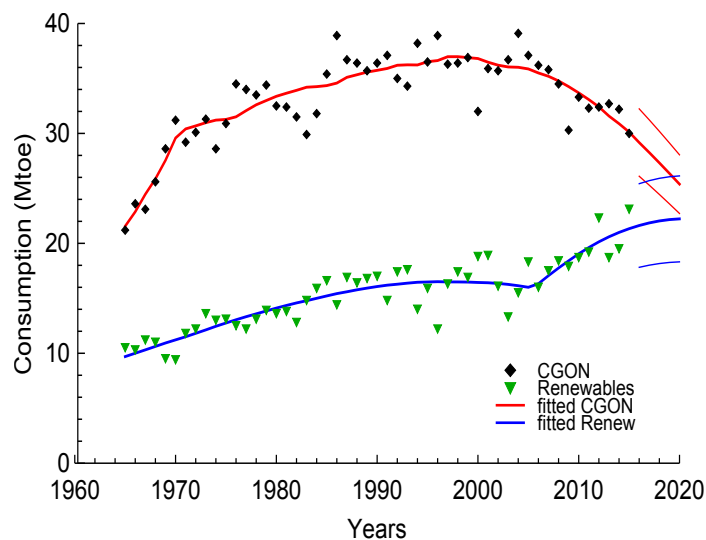
Hsu, S.B., Ruan S., Yan T.C. (2015). Analysis of three species Lotka–Volterra food web models with omnivory *Journal of Mathematical Analysis and Applications*, 426(2), pp. 659-687.

## An example from a statistical point of view

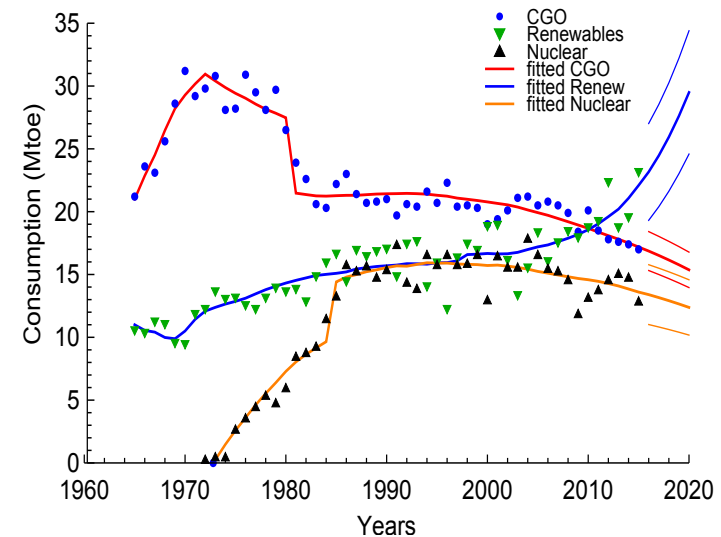
(Furlan et al., 2021)

Yearly energy consumptions (provided by BP, in Mtoe) for Sweden

### CGON vs. Renewables



### CGO vs N vs. Renewables



Furlan, C., Mortarino, C. and Zahangir, M. S. (2021). Interaction among three-substitute products: an extended innovation diffusion model. *Statistical Methods & Applications*, 30, pp. 269–293.

### 3CM (3 Competitor Model)

$$\begin{aligned}
 z'_1(t) &= m \left\{ \left[ p_{1\alpha} + (q_{1\alpha} + \delta_\alpha) \frac{z_1(t)}{m} + q_{1\alpha} \frac{z_2(t)}{m} \right] (1 - I_{t>c_2}) + \right. \\
 &\quad \left. + \left[ p_{1\beta} + (q_{1\beta} + \delta_\beta) \frac{z_1(t)}{m} + q_{1\beta} \frac{z_2(t)}{m} + q_{1\beta} \frac{z_3(t)}{m} \right] I_{t>c_2} \right\} R(t) x_1(t) \\
 z'_2(t) &= m \left\{ \left[ p_{2\alpha} + (q_{2\alpha} - \delta_\alpha) \frac{z_1(t)}{m} + q_{2\alpha} \frac{z_2(t)}{m} \right] (1 - I_{t>c_2}) + \right. \\
 &\quad \left. + \left[ p_{2\beta} + q_{2\beta} \frac{z_1(t)}{m} + (q_{2\beta} + \delta_\beta) \frac{z_2(t)}{m} + q_{2\beta} \frac{z_3(t)}{m} \right] I_{t>c_2} \right\} R(t) x_2(t) \\
 z'_3(t) &= m \left\{ \left[ p_3 + (q_3 - \delta_\beta) \frac{z_1(t)}{m} + (q_3 - \delta_\beta) \frac{z_2(t)}{m} + q_3 \frac{z_3(t)}{m} \right] I_{t>c_2} \right\} R(t) x_3(t) \\
 m &= m_\alpha (1 - I_{t>c_2}) + m_\beta I_{t>c_2} \\
 z(t) &= z_1(t) + z_2(t) + z_3(t) I_{t>c_2}
 \end{aligned}$$