

## INTRODUCTION

**Procrustes problem:** matches matrices using **similarity transformations** by minimizing their Frobenius distance.

Most of the applications comprise **spatial coordinates**. The extension to **high dimensional** context lists:

- **Ill-posed problem;**
- **Polynomial time complexity** in no. of variables to align.

## PERTURBATION MODEL (Goodall, 1991)

Let  $\{X_i \in \mathbb{R}^{n \times m}\}_{i=1, \dots, N}$  be a set of matrices to be aligned:

$$X_i = \alpha_i(M + E_i)R_i^T + \mathbf{1}_n^T t_i \quad \text{subject to} \quad R_i \in O(m)$$

- $E_i \sim \mathcal{MN}_{n,m}(0, \Sigma_n, \Sigma_m)$ ;
- $R_i \in O(m)$ ;
- $M \in \mathbb{R}^{n \times m}$  is the **shared matrix**;
- $\alpha_i \in \mathbb{R}^+$  is the **isotropic scaling**;
- $t_i \in \mathbb{R}^{1 \times m}$  defines the **translation vector**.

Consider the SVD of  $X_i^T \Sigma_n^{-1} M \Sigma_m^{-1} = U_i^T D_i V_i$ :

- $\hat{R}_i = U_i^T V_i$ ;
- $\hat{\alpha}_{iR_i} = \|\Sigma_m^{1/2} \hat{R}_i^T X_i \Sigma_n^{-1/2}\|_F^2 / \text{tr}(D_i)$ .

Consider  $N$  independent  $X_i$ . If  $M, \Sigma_m, \Sigma_n$  are unknown:

**Require:**  $X_i, T, \max It, \forall i = 1, \dots, N$

**Ensure:**  $\hat{X}_i \forall i = 1, \dots, N$

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1:  $\hat{M} = \sum_{i=1}^N X_i / N, \hat{\alpha}_i = 1, \hat{\Sigma}_n; \text{old} = \hat{\Sigma}_n = I_n, \hat{\Sigma}_m; \text{old} = \hat{\Sigma}_m = I_m, \text{count} = 0, \text{dist} = \text{Inf}$ 
2: while  $\text{dist} > T$  OR  $\text{count} < \max It$  do
3:   for  $i = 1$  to  $N$  do
4:      $U_i D_i V_i^T = \text{SVD}(X_i^T \hat{\Sigma}_n^{-1} \hat{M} \hat{\Sigma}_m^{-1})$ 
5:      $\hat{R}_i = U_i V_i^T$ 
6:      $\hat{X}_i = X_i \hat{R}_i$ 
7:      $\hat{\alpha}_{iR_i} = \|\hat{\Sigma}_m^{-1/2} \hat{R}_i^T X_i \hat{\Sigma}_n^{-1/2}\|_F^2 / \text{tr}(D_i)$ 
8:      $\hat{X}_i = \hat{\alpha}_{iR_i}^{-1} \hat{X}_i$       > Update  $X_i$ 
9:   end for
10:   $\hat{M}_{\text{old}} = \hat{M}$       > Save  $\hat{M}$ 
11:   $\hat{M} = \sum_{i=1}^N \hat{X}_i / N$       > Update  $\hat{M}$ 
12:   $\hat{\Sigma}_n = g(\hat{\Sigma}_n, \hat{M}, X_i), \hat{\Sigma}_m = g(\hat{\Sigma}_m, \hat{M}, X_i)$ 
13:  while  $\|\hat{\Sigma}_n - \hat{\Sigma}_n; \text{old}\|^2 > \epsilon_1$  ||  $\|\hat{\Sigma}_m - \hat{\Sigma}_m; \text{old}\|^2 > \epsilon_2$  do
14:     $\hat{\Sigma}_n; \text{old} = \hat{\Sigma}_n, \hat{\Sigma}_m; \text{old} = \hat{\Sigma}_m$ 
15:     $\hat{\Sigma}_n = g(\hat{\Sigma}_n, \hat{M}, X_i), \hat{\Sigma}_m = g(\hat{\Sigma}_m, \hat{M}, X_i)$ 
16:  end while
17:   $\text{dist} = \|\hat{M} - \hat{M}_{\text{old}}\|^2, \text{count} = \text{count} + 1.$ 
18: end while

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## ISSUES:

- If  $Z \in O(m)$ , then  $\{\hat{R}_i Z\}_{i=1, \dots, N}$  still valid ML solutions.
- If  $n < m$ , then the ML estimate for  $R_i$  is **not unique**.

## PROMISES MODEL (Andreella and Finos, 2022)

### HOW TO SOLVE THE ILL-POSED PROBLEM?

→ Prior on  $R_i$ : **von Mises-Fisher distribution**:

$$f(R_i) = C(F, k) \exp\{\text{tr}(k F^T R_i)\}$$

- $F \in \mathbb{R}^{m \times m}$  is the **location parameter**,
- $k \in \mathbb{R}^+$  is the **concentration parameter**.

The **mode** equals the polar part of  $F$ .

- the posterior distribution is **conjugate** with location parameter:

$$F^* = X_i^T \Sigma_n^{-1} M \Sigma_m^{-1} + k F$$

- Consider the SVD of  $F^*$ :
  - $\hat{R}_i = U_i^T V_i$ ;
  - $\hat{\alpha}_{iR_i} = \|\Sigma_m^{1/2} \hat{R}_i^T X_i \Sigma_n^{-1/2}\|_F^2 / \text{tr}(D_i)$ .
- If  $F$  has full rank, the MAP estimates for  $R_i$  are unique.

Consider  $N$  independent  $X_i$ . If  $M, \Sigma_m, \Sigma_n$  are unknown → we modify line 5 of the perturbation model's algorithm.

## EFFICIENT PROMISES MODEL

### HOW TO SOLVE POLYNOMIAL TIME COMPLEXITY PROBLEM?

The ProMises model provides unique solutions but at each step, we perform  $N$  SVD of  $m \times m$  matrices, i.e.,  $O(m^3)$ .

Let  $Q_i$  be the semi-orthogonal matrix from the **thin** SVD of  $X_i$ . Then:

$$\begin{aligned} \max_{R_i \in O(m)} \text{tr}(R_i^T X_i^T \Sigma_n^{-1} X_j \Sigma_m^{-1} + k F) = \\ \max_{R_i^* \in O(n)} \text{tr}\{R_i^{*T} (Q_i^T X_i^T \Sigma_n^{-1} X_j \Sigma_m^{-1} Q_j^T + k F^*)\}, \end{aligned}$$

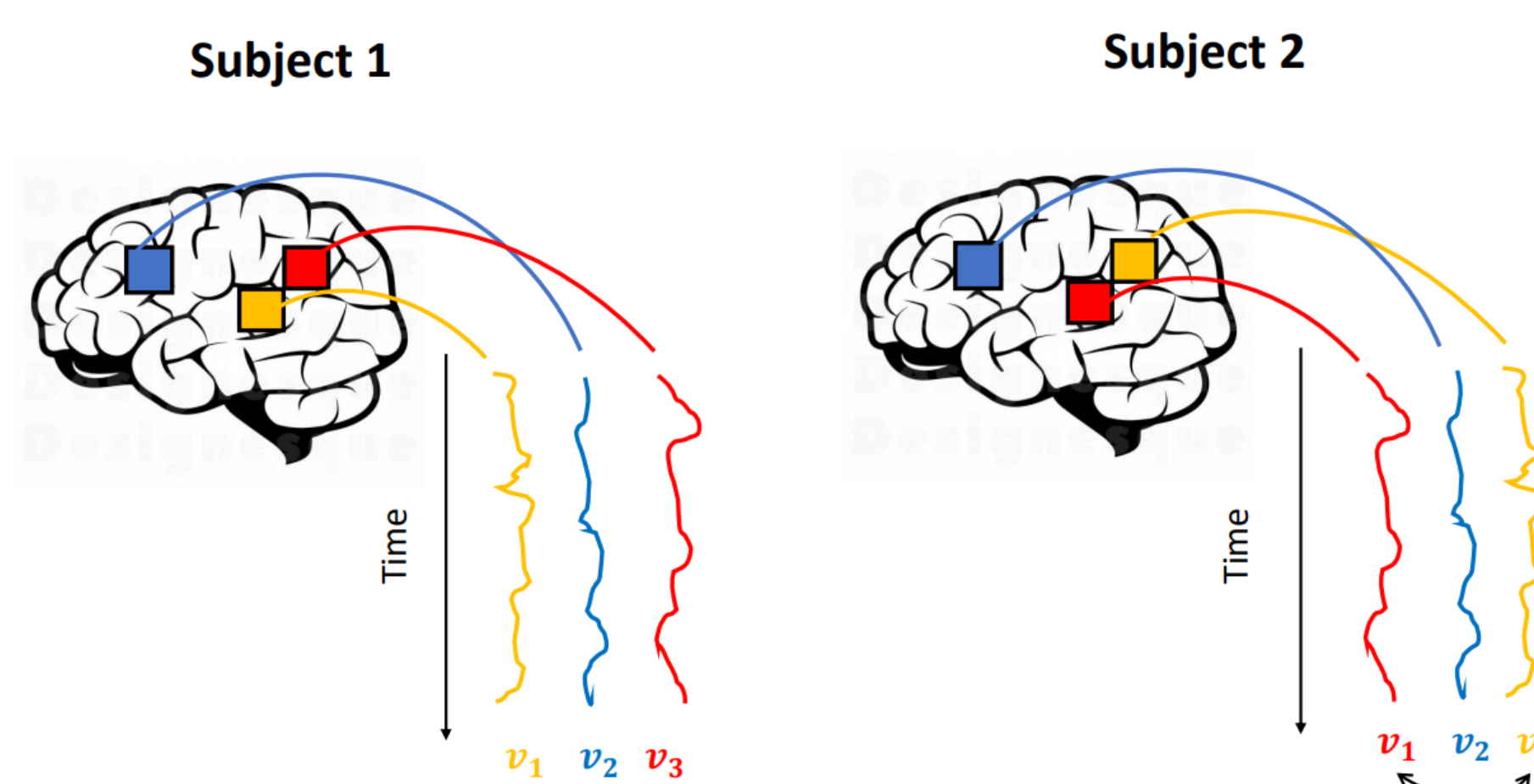
$\{X_i Q_i \in \mathbb{R}^{n \times n}\}_{i=1, \dots, N}$  are aligned by the perturbation or ProMises model. Then,  $\{Q_i^T\}_{i=1, \dots, N}$  projects back the aligned matrices to the original  $n \times m$ -size matrices.

The lines to reduce the dimensions of  $X_i$  are added on the perturbation model's algorithm → **Time complexity** from  $O(m^3)$  to  $O(mn^2)$ , and the **space** one from  $O(m^2)$  to  $O(mn)$ .

## FMRI DATA APPLICATION

Each subject's **brain activation** is represented by a matrix:

- **Rows** represent the **stimuli/time points** → correspondence btw subject (time-synchronized),
- **Columns** represent the **voxels** → not correspondence btw subject:



**AIM:** Represent the neural responses to stimuli into a **common high-dimensional space**, instead of canonical anatomical space → variability of functional topographies loci.

**SOLUTION:** Procrustes-based models.

**High-dimensional problem** → each voxel is one dimension:

1. Perturbation model combines any voxel inside the brain without considering **anatomical locations**;
2. non-identifiability of  $R_i$  → loss of **topological interpretability** of the results;
3. **computational load** → SVD of many square matrices of dimensions  $\approx 200.000$ , i.e., the number of voxels.

We solve these issues using the **efficient ProMises model!**

The anatomical information are inserted into  $F$  → defined as an **Euclidean similarity matrix** using the **3D anatomical coordinates**  $x, y$  and  $z$  of each voxel:

$$F = \left[ \exp \left\{ -\sqrt{(x_i - x_j)^2 + (y_i - y_j)^2 + (z_i - z_j)^2} \right\} \right],$$

where  $i, j = 1, \dots, m$ . So:

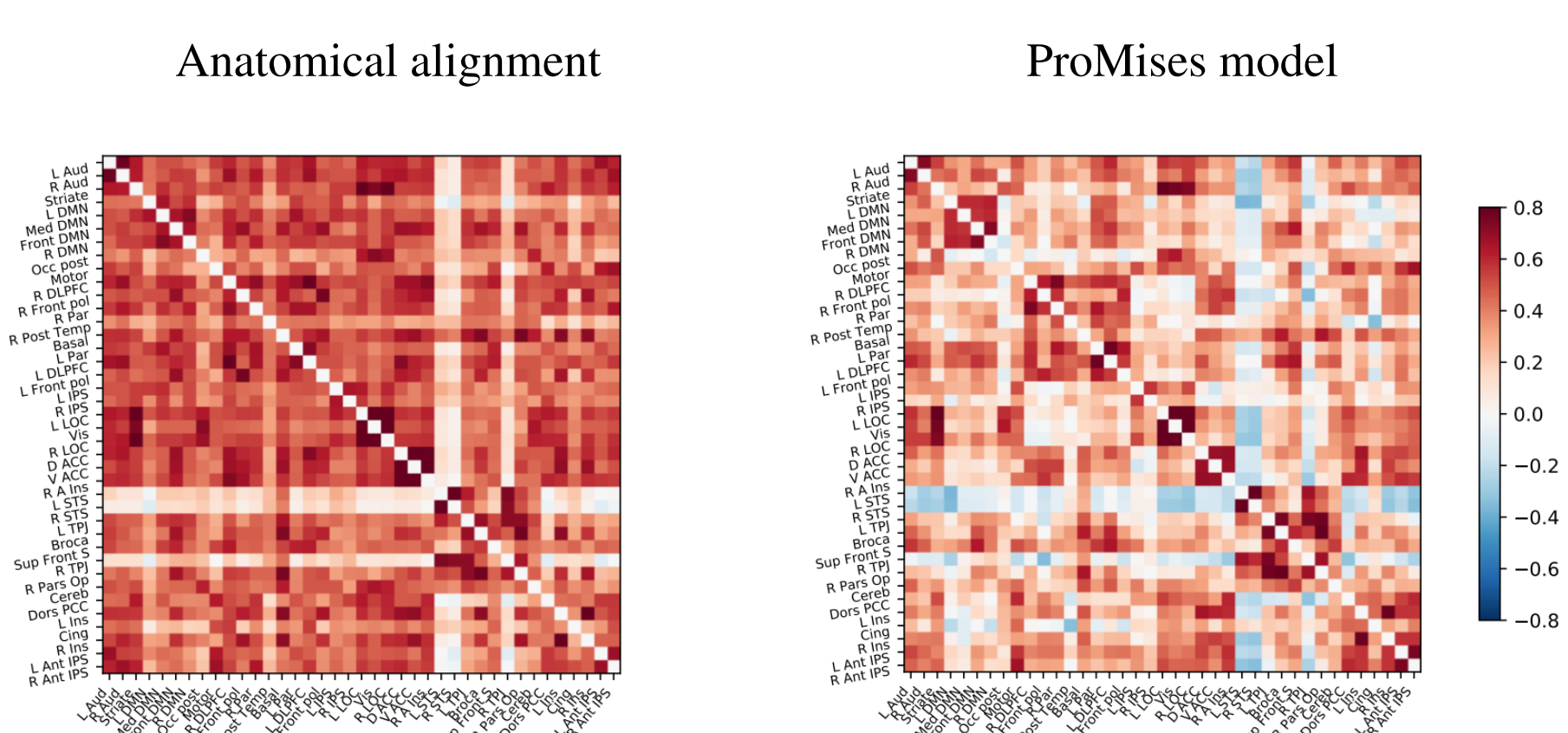
- Voxels with the **same spatial location** combined with weights 1;
- weights **decrease** as the voxels are more **spatially distant**.

## 1. FUNCTIONAL CONNECTIVITY

We align brain images consisting of neural activations of 18 subjects passively listening to vocal and non-vocal sounds.

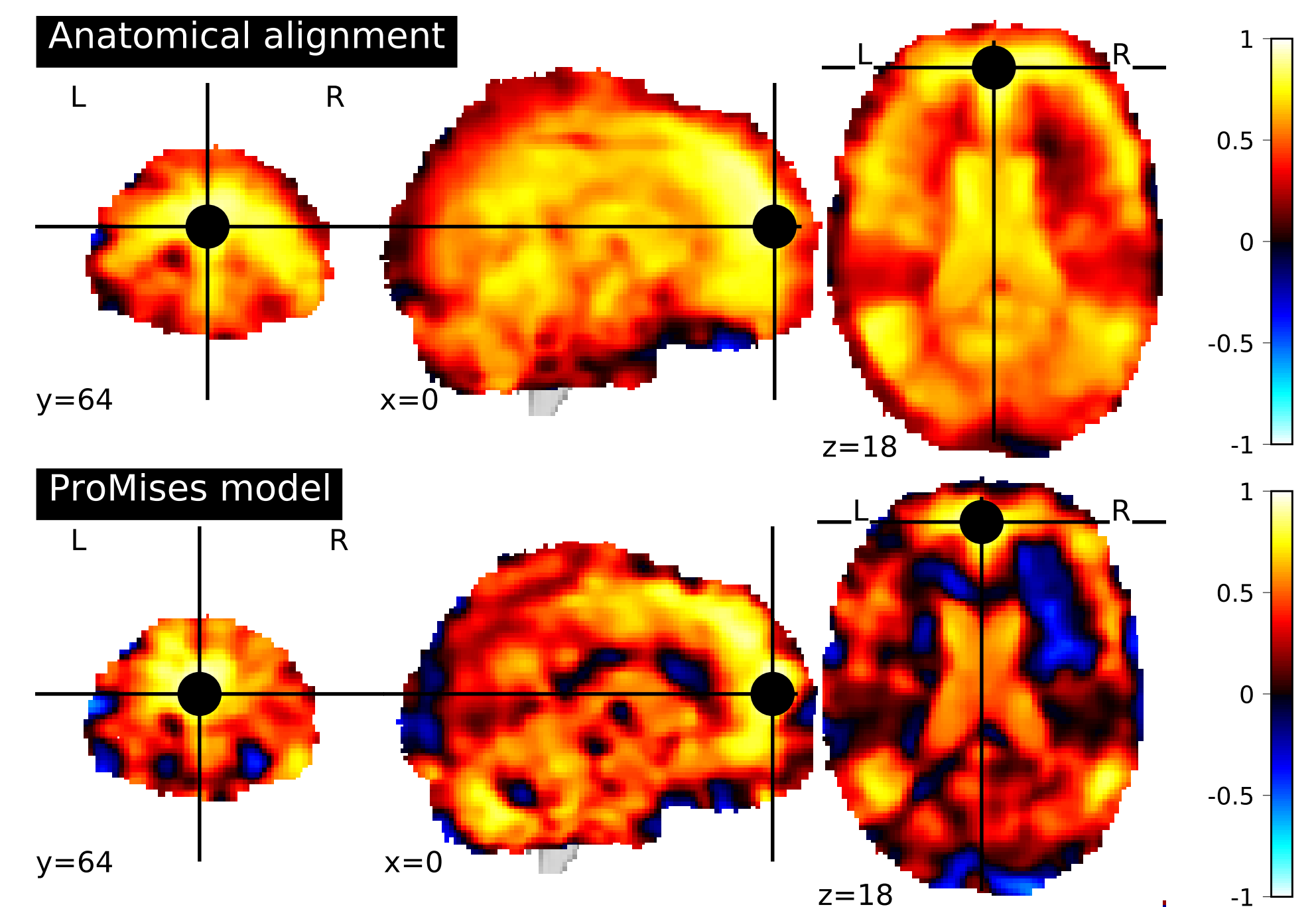
### a. Region of interest correlation analysis

**Functional correlation** are computed btw the region of interest from a standard atlas.



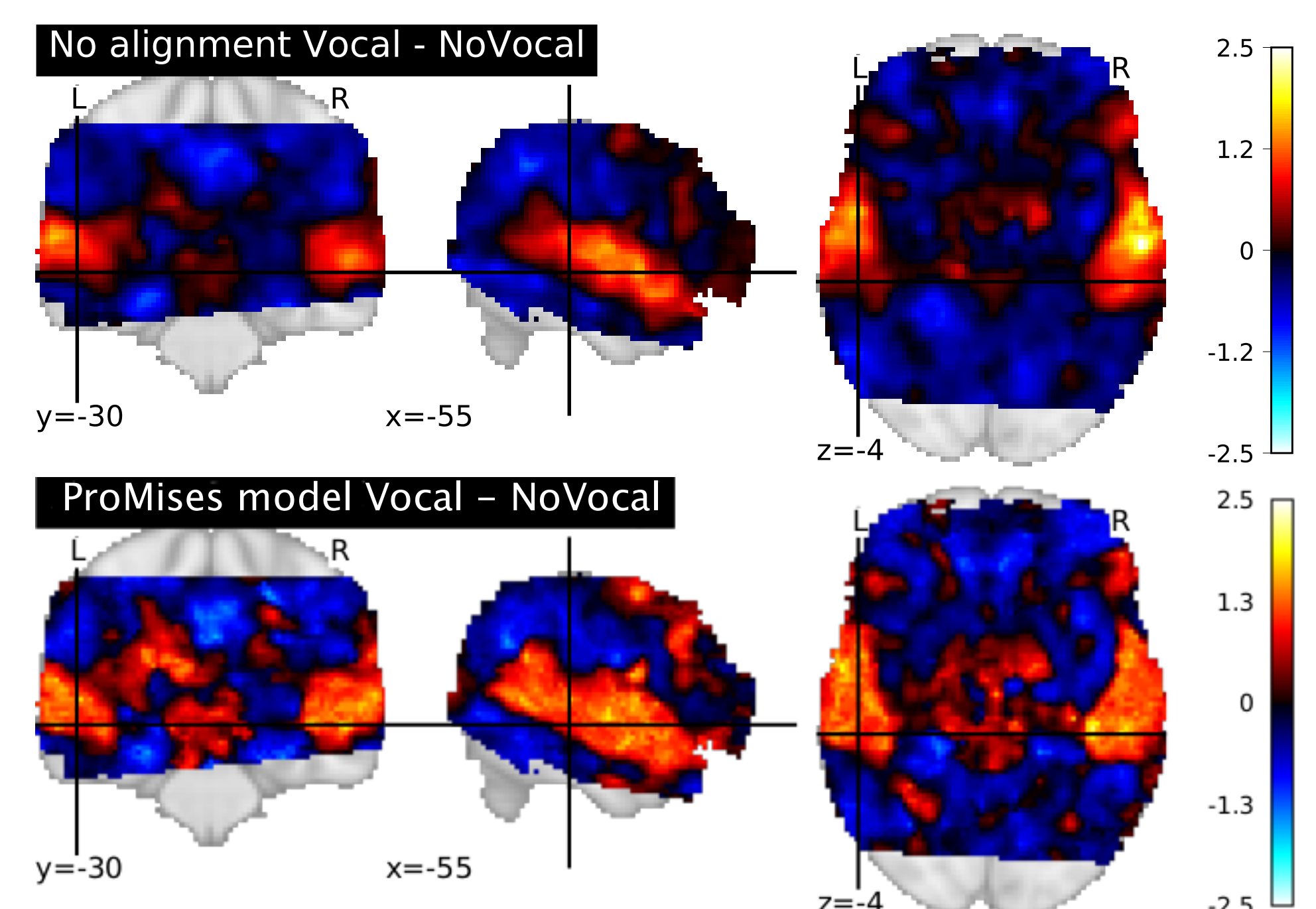
## b. Seed-based correlation analysis

**Functional correlation** are computed btw a seed (Frontal Pole/ black dot) and any voxel.



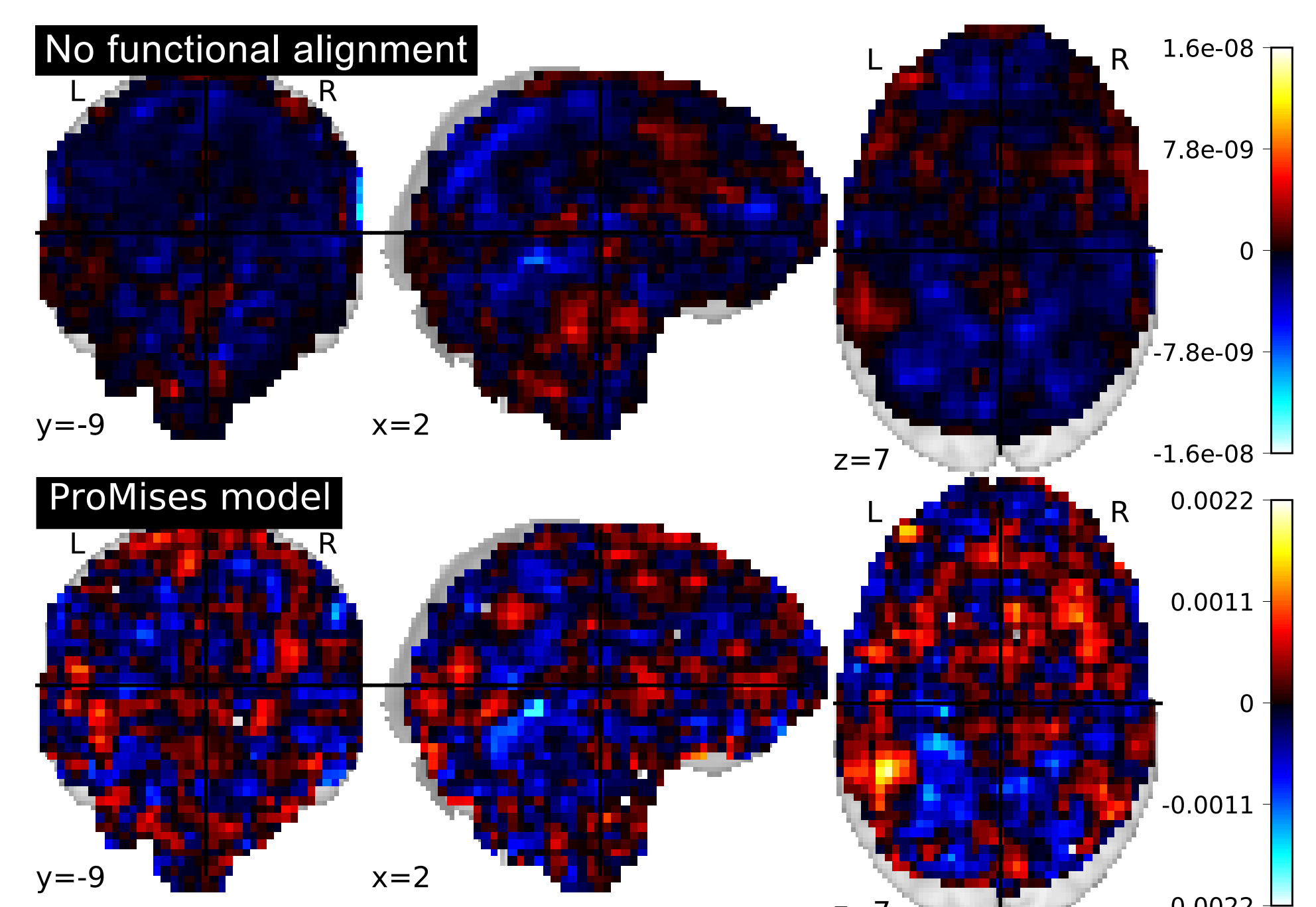
## 2. INFERENCE ANALYSIS

Same data as before, but we compute **t-tests** to analyze the difference of neural activation during the two stimuli.



## 3. CLASSIFICATION ANALYSIS

We align the brain images of 10 subjs watching images of faces and objects, and we **classify** it by multi-class SVM.



## TAKE HOME MESSAGES

The issues of the perturbation model are solved:

- **Unique** and **interpretable**  $\hat{R}_i$ ;
- Efficient approach permits the **applicability when  $m \gg n$** ;
- $F$  leads  $R_i$ 's estimation (anatomical position in fMRI).

## References

Andreella, A., Finos, L. Procrustes analysis for high-dimensional data. *Psychometrika*, 2022, 1 – 17.

Andreella, A., Finos, L., Lindquist, M. (2022) Enhanced hyperalignment via spatial prior information. *arXiv:2209.07960*

Goodall, C. (1991). Procrustes methods in the statistical analysis of shape. *JRSS: Series B* 53 (2), 285 – 321.

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